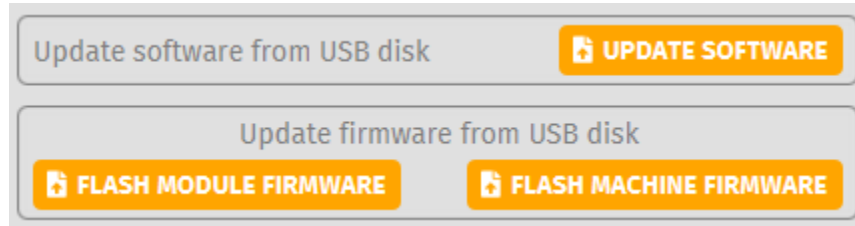


TITAN 25T LANGMUIR SYSTEMS

Instructions to update to 24.1.2:

1. Download the update following file and save it to a flash drive.
<https://drive.google.com/file/d/1UCQ5zKRIEm52MbCmESolsxnIML52Ao09/view?usp=sharing>
2. Start your machine and insert the flash drive into the front USB port.
3. Go to the Settings tab in BendControl.
4. Select the button labeled "Update Software". A popup will appear, select "Yes".



5. A file explorer will open. Select your flash drive from the list on the left of the file explorer. It should appear below "Downloads" and above "Documents".
6. Once opened, select the file titled "bendcontrol_24.1.2.jar". Once selected, tap the "Open" button in the top right corner of the file explorer.
7. After a few seconds, a popup will appear, select "Restart System".
8. Your machine will now update. Once complete, BendControl will boot up. This whole process will take a few minutes.

Change notes:

- Fixed a bug where BendControl would freeze during the Backgauge Bump-off step during a programmed bend.
- Fixed a bug where naming Backgauge coordinates would not save once edited.
- Fixed a bug where programs would freeze if the pedal was released too early the previous time the program was run.
- Fixed a bug where adding a bend with errors to a program would lock the Add Bend button.
- Added system information in the header bar displaying the current system load and CPU temperature. This will assist in debugging to determine if the computer inside of your Titan is being overloaded or running at too high of a temperature.